

# Hom-Lie structures on 3-dimensional skew symmetric algebras

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# Introduction

The study of Hom-Lie algebras is attributed to Hartwig, Larsson, and Silvestrov. This involves an introduction of a new linear map (twist) to the Lie algebra case.

## Definition

[2] A Hom-Lie algebra is a triple  $(V, [\cdot, \cdot], \alpha)$  consisting of a linear space  $V$ , bilinear map  $[\cdot, \cdot] : V \times V \rightarrow V$  and a linear space homomorphism  $\alpha : V \rightarrow V$  satisfying

$$[x, y] = -[y, x] \quad (\text{skew - symetry}) \quad (1)$$

$$\bigcirc_{x,y,z} [\alpha(x), [y, z]] = 0 \quad (\text{Hom - Jacobi identity}) \quad (2)$$

for all  $x, y, z \in V$ , where  $\bigcirc_{x,y,z}$  denotes summation over the cyclic permutation on  $x, y, z$ .

Hom-Lie structures, denoted by  $\text{HomLie}(\mu)$ , is the space of all linear endomorphisms that satisfy the Hom-Jacobi identity for some skew symmetric algebra  $L$ .

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That is the **vector subspace**

$$\text{HomLie}(\mu) = \{ \alpha \in \text{End } V \mid \circlearrowleft_{x,y,z} [\alpha(x), [y, z]] = 0, x, y, z \in L \}.$$

# Equations of structure constants

Let  $\{e_1, e_2, \dots, e_n\}$  be basis for  $V$ .

The structure constant equations are given by;

$$[e_i, e_j] = \sum_{s=1}^n C_{ij}^s e_s \quad (3)$$

and

$$\alpha(e_i) = \sum_{t=1}^n a_{it} e_t \quad (4)$$

Replacing 3 and 4 in the Hom-Jacobi identity, we have a system of polynomial equations;

$$\sum_{s,t=1}^n a_{it} C_{jk}^s C_{ts}^r + a_{jt} C_{ki}^s C_{ts}^r + a_{kt} C_{ij}^s C_{ts}^r = 0, \quad r = 1, 2, \dots, n. \quad (5)$$

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Writing the equations as linear in  $a'_{it}s$ , we rewrite 5 as;

$$\sum_{t=1}^n \left\{ a_{it} \left( \sum_{s=1}^n C_{jk}^s C_{ts}^r \right) + a_{jt} \left( \sum_{s=1}^n C_{ki}^s C_{ts}^r \right) + a_{kt} \left( \sum_{s=1}^n C_{ij}^s C_{ts}^r \right) \right\} = 0, \quad (6)$$

$$1 \leq i < j < k \leq n, \quad r = 1, 2, \dots, n.$$



Thus 6 becomes

$$Ma_{\alpha} = 0$$

where column matrix  $a_{\alpha}$  is;

$$a_{\alpha} = \begin{pmatrix} a_{11} \\ \vdots \\ a_{n1} \\ a_{12} \\ \vdots \\ a_{n2} \\ \vdots \\ \vdots \\ a_{nn} \end{pmatrix}$$

$M$  is a matrix with  $n^2$  columns and  $\binom{n}{3} \cdot n$  rows.

## 3–Dimensional Hom Lie algebras

In three dimension Hom-Lie algebras the system of polynomial equations is obtained from 5. Together with the skew- symmetry condition, the equation becomes;

$$\sum_{\substack{m,n=1 \\ m < n}}^3 \left( \bigcirc_{i,j,k} (a_{im} C_{jk}^n C_{mn}^r - a_{in} C_{jk}^m C_{mn}^r) \right) = 0 \quad (7)$$

for  $r = 1, 2, 3$  and  $1 \leq i < j < k \leq 3$ , where the symbol  $\bigcirc_{i,j,k}$  denotes a summation over the cyclic permutation on  $i, j, k$ .

Matrix  $M$  is a 3 by 9 matrix given as;

$$M = \begin{pmatrix} M_{1,1} & M_{1,2} & M_{1,3} & M_{1,4} & M_{1,5} & M_{1,6} & M_{1,7} & M_{1,8} & M_{1,9} \\ M_{2,1} & M_{2,2} & M_{2,3} & M_{2,4} & M_{2,5} & M_{2,6} & M_{2,7} & M_{2,8} & M_{2,9} \\ M_{3,1} & M_{3,2} & M_{3,3} & M_{3,4} & M_{3,5} & M_{3,6} & M_{3,7} & M_{3,8} & M_{3,9} \end{pmatrix}$$

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$$M_{r,1} = (C_{23}^2 C_{12}^r + C_{23}^3 C_{13}^r)$$

$$M_{r,2} = (-C_{13}^2 C_{12}^r - C_{13}^3 C_{13}^r)$$

$$M_{r,3} = (C_{12}^2 C_{12}^r + C_{12}^3 C_{13}^r)$$

$$M_{r,4} = (C_{23}^3 C_{23}^r - C_{23}^1 C_{12}^r)$$

$$M_{r,5} = (C_{13}^1 C_{12}^r - C_{13}^3 C_{23}^r)$$

$$M_{r,6} = (C_{12}^3 C_{23}^r - C_{12}^1 C_{12}^r)$$

$$M_{r,7} = (-C_{23}^1 C_{13}^r - C_{23}^2 C_{23}^r)$$

$$M_{r,8} = (C_{13}^1 C_{13}^r + C_{13}^2 C_{23}^r)$$

$$M_{r,9} = (-C_{12}^1 C_{13}^r - C_{12}^2 C_{23}^r)$$

for  $r = 1, 2, 3$ .

# Hom-Lie Structures Dimension

$M$  represents a linear map  $L : \mathbb{K}^9 \rightarrow \mathbb{K}^3$ , and hence

$a_\alpha = (a_{11} \ a_{21} \ a_{31} \ a_{12} \ a_{22} \ a_{32} \ a_{13} \ a_{23} \ a_{33})^t$  must be in the  $\ker(L)$  for us to realize a Hom-Lie algebra.

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$$\implies 6 \leq \dim \text{HomLie}(\mu) \leq 9$$

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Let  $C$  the matrix of structure constants given as

$$C = \begin{pmatrix} C_{12}^1 & C_{12}^2 & C_{12}^3 \\ C_{13}^1 & C_{13}^2 & C_{13}^3 \\ C_{23}^1 & C_{23}^2 & C_{23}^3 \end{pmatrix}$$

## Proposition

*Let  $L$  be a 3-dimensional skew symmetric algebra with structure constants  $\{C_{ij}^k\}_{i < j}$  and  $C$  be the matrix of structure constants. The dimension of the space of possible endomorphisms,  $\text{HomLie}(\mu)$ , attains minimum dimension 6, if and only if  $\det C$  is non-zero.*

## Proof.

For  $\text{Rank}(M) = 3$ , then there exists a non-zero sub-determinant of a  $3 \times 3$  sub-matrix of  $M$ .

From the computations all the non-zero sub-determinants have  $\det C$  as a factor.





For example;

$$C_{23}^3(C_{13}^2 C_{23}^3 - C_{13}^3 C_{23}^2)(\det C)$$

$$-C_{13}^3(C_{13}^2 C_{23}^3 - C_{13}^3 C_{23}^2)(\det C)$$

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⋮

# Rank $C = 2$

## Proposition

*Let  $L$  be a 3-dimensional skew symmetric algebra with structure constants  $\{C_{ij}^k\}_{i < j}$  and  $C$  be the matrix of structure constants. If rank  $C$  is 2 then the dimension of the space of possible endomorphisms,  $\text{HomLie}(\mu)$ , is 7.*

## Proof.

From previous results, we see that if  $C$  is not of full rank then  $\dim \text{HomLie}(\mu) \geq 7$ . From computations, if  $\text{rank}(C) = 2$ , there exists a non-zero sub-determinant of a  $2 \times 2$  sub-matrix of  $M$ .

We investigate all possible cases for  $\text{rank } C = 2$  (linear dependency of rows and/or zero rows) and compare in the list of the  $2 \times 2$  sub-determinants of  $M$ . For each case, there exists at least one such non-zero subdeterminant. □

Rank  $C = 1$ , with  $\dim \text{HomLie}(\mu) = 8$

From the results it follows that if rank  $C$  is 1 then the dimension of  $\text{HomLie}(\mu) > 7$ .

However, if rank  $C = 1$  this dimension can either be 8 or 9.

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However, if rank  $C = 1$  this dimension can either be 8 or 9.

$\dim \text{HomLie}(\mu) = 8$

$$\mathfrak{e}'_1 = \begin{pmatrix} C_{12}^1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, C_{12}^1 \neq 0 \quad \mathfrak{e}'_2 = \begin{pmatrix} 0 & C_{12}^2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, C_{12}^2 \neq 0$$

$$\mathfrak{e}'_3 = \begin{pmatrix} 0 & 0 & 0 \\ C_{13}^1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, C_{13}^1 \neq 0 \quad \mathfrak{e}'_4 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & C_{13}^3 \\ 0 & 0 & 0 \end{pmatrix}, C_{13}^3 \neq 0$$

$$\mathfrak{e}'_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & C_{23}^2 & 0 \end{pmatrix}, C_{23}^2 \neq 0 \quad \mathfrak{e}'_5 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & C_{23}^3 \end{pmatrix}, C_{23}^3 \neq 0$$

Rank  $C = 1$ , with  $\dim \text{HomLie}(\mu) = 9$

$$\mathfrak{e}_1 = \begin{pmatrix} C_{23}^3 & C_{12}^2 & -\frac{C_{12}^2 C_{23}^3}{C_{13}^1} \\ C_{13}^1 & \frac{C_{12}^2 C_{13}^1}{C_{23}^3} & -C_{12}^2 \\ -\frac{C_{13}^1 C_{23}^3}{C_{12}^2} & -C_{13}^1 & C_{23}^3 \end{pmatrix} \quad C_{12}^2, C_{13}^1, C_{23}^3 \neq 0$$

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$$\mathfrak{e}_2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ C_{23}^1 & 0 & 0 \end{pmatrix}, C_{23}^1 \neq 0 \quad \mathfrak{e}_3 = \begin{pmatrix} C_{23}^3 & 0 & C_{12}^3 \\ 0 & 0 & 0 \\ \frac{(C_{23}^3)^2}{C_{12}^3} & 0 & C_{23}^3 \end{pmatrix}, C_{12}^3 \neq 0$$

Rank  $C = 1$ , with  $\dim \text{HomLie}(\mu) = 9$

$$\mathfrak{g}_4 = \begin{pmatrix} 0 & 0 & 0 \\ C_{13}^1 & C_{13}^2 & 0 \\ -\frac{(C_{13}^1)^2}{C_{13}^2} & -C_{13}^1 & 0 \end{pmatrix}, C_{13}^2 \neq 0$$

$$\mathfrak{g}_5 = \begin{pmatrix} 0 & C_{12}^2 & C_{12}^3 \\ 0 & \frac{(C_{12}^2)^2}{C_{12}^3} & -C_{12}^2 \\ 0 & 0 & 0 \end{pmatrix}, C_{12}^3 \neq 0$$

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## Proposition

*If two skew-symmetric algebras  $(L, \mu)$  and  $(L', \mu')$  are isomorphic, then  $\text{HomLie}(\mu)$  is isomorphic to  $\text{HomLie}(\mu')$ .*



## Proof.

Let  $\phi : L \rightarrow L'$  be the isomorphism of the algebras. Let  $\alpha \in \text{HomLie}(\mu)$  and  $\beta \in \text{HomLie}(\mu')$ . The isomorphism between the Hom-Lie structures  $\varphi : \text{HomLie}(\mu) \rightarrow \text{HomLie}(\mu')$  is defined by  $\beta = \varphi(\alpha) := \phi \circ \alpha \circ \phi^{-1}$ . Given  $x, y, z \in L$ , then there exists  $x', y', z' \in L'$  as images under the isomorphism  $\phi$ , that is  $\phi(x) = x', \phi(y) = y'$  and  $\phi(z) = z'$ .  $\beta = \phi \circ \alpha \circ \phi^{-1}$  implies  $\beta(x') = \phi(\alpha(x)), \beta(y') = \phi(\alpha(y))$  and  $\beta(z') = \phi(\alpha(z))$ .

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We show that if  $\alpha \in \text{HomLie}(\mu)$  then  $\beta \in \text{HomLie}(\mu')$ .

$$\begin{aligned} & \mu'(\beta(x'), \mu'(y', z')) + \mu'(\beta(y'), \mu(z', x')) + \mu'(\beta(z'), \mu'(x', y')) \\ &= \mu'(\phi(\alpha(x)), \mu'(\phi(y), \phi(z))) + \mu'(\phi(\alpha(y)), \mu(\phi(z), \phi(x))) \\ & \quad + \mu'(\phi(\alpha(z)), \mu'(\phi(x), \phi(y))) \\ &= \phi[\mu((\alpha(x)), \mu(y, z)) + \mu((\alpha(y)), \mu(z, x)) + \mu((\alpha(z)), \mu(x, y))] \\ &= 0 \end{aligned}$$



## Example

The Heisenberg Lie algebra:  $[e_1, e_2] = e_3$ ,  $[e_1, e_3] = 0$ ,  $[e_2, e_3] = 0$

$$C = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \implies \dim \text{HomLie}(\mu) = 9.$$

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The Lie algebra:

$$[f_1, f_2] = -f_1 - f_2 + f_3, \quad [f_1, f_3] = -f_1 - f_2 + f_3, \quad [f_2, f_3] = f_1 + f_2 - f_3$$

is isomorphic to the Heisenberg Lie algebra. Here,

$$C = \begin{pmatrix} -1 & -1 & 1 \\ -1 & -1 & 1 \\ 1 & 1 & -1 \end{pmatrix} \implies \dim \text{HomLie}(\mu) = 9.$$

These algebras are found in classes  $\mathfrak{C}_3$  and  $\mathfrak{C}_1$  respectively.

## Example

Simple Lie algebra,  $\mathfrak{sl}(2, \mathbb{C})$ :  $[e_1, e_2] = -2e_1$ ,  $[e_1, e_3] = e_2$ ,  $[e_2, e_3] = -2e_3$






$$C = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \implies \dim \text{HomLie}(\mu) = 6.$$

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$$C = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \implies \dim \text{HomLie}(\mu) = 6.$$

$$\alpha = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 2a_{13} & a_{22} & a_{31} \\ 2a_{12} & a_{32} & a_{22} \end{pmatrix}, \text{ with 6 parameters } a_{11}, a_{12}, a_{13}, a_{13}, a_{22}, a_{32} \in \mathbb{C}.$$

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Thank you!